



University of
Zurich^{UZH}

Zurich Open Repository and
Archive

University of Zurich
Main Library
Strickhofstrasse 39
CH-8057 Zurich
www.zora.uzh.ch

Year: 2006

The nonlinear membrane energy: Variational derivation under the constraint “ $\det u > 0$ ”

Anza Hafsa, O ; Mandallena, J P

Abstract: Acerbi, Buttazzo and Percivale gave a variational definition of the nonlinear string energy under the constraint “ $\det u > 0$ ” (see [E. Acerbi, G. Buttazzo, D. Percivale, A variational definition of the strain energy for an elastic string, *J. Elasticity* 25 (1991) 137–148]). In the same spirit, we obtain the nonlinear membrane energy under the simpler constraint “ $\det u > 0$ ”.

DOI: <https://doi.org/10.1016/j.matpur.2006.01.004>

Other titles: The nonlinear membrane energy: variational derivation under the constraint “ $\det \nabla u > 0$ ”

Posted at the Zurich Open Repository and Archive, University of Zurich

ZORA URL: <https://doi.org/10.5167/uzh-21588>

Journal Article

Accepted Version

Originally published at:

Anza Hafsa, O; Mandallena, J P (2006). The nonlinear membrane energy: Variational derivation under the constraint “ $\det u > 0$ ”. *Journal de Mathematiques Pures et Appliquees*, 86(2):100-115.

DOI: <https://doi.org/10.1016/j.matpur.2006.01.004>

**THE NONLINEAR MEMBRANE ENERGY: VARIATIONAL
DERIVATION UNDER THE CONSTRAINT “ $\det \nabla u > 0$ ”**

OMAR ANZA HAFSA AND JEAN-PHILIPPE MANDALLENNA

ABSTRACT. In [4] we gave a variational definition of the nonlinear membrane energy under the constraint “ $\det \nabla u \neq 0$ ”. In this paper we obtain the nonlinear membrane energy under the more realistic constraint “ $\det \nabla u > 0$ ”.

1. INTRODUCTION

Consider an elastic material occupying in a reference configuration the bounded open set $\Sigma_\varepsilon \subset \mathbb{R}^3$ given by

$$\Sigma_\varepsilon := \Sigma \times \left] -\frac{\varepsilon}{2}, \frac{\varepsilon}{2} \right[,$$

where $\varepsilon > 0$ is very small and $\Sigma \subset \mathbb{R}^2$ is Lipschitz, open and bounded. A point of Σ_ε is denoted by (x, x_3) with $x \in \Sigma$ and $x_3 \in]-\frac{\varepsilon}{2}, \frac{\varepsilon}{2}[$. Let $W : \mathbb{M}^{3 \times 3} \rightarrow [0, +\infty]$ be the stored-energy function supposed to be *continuous* and *coercive*, i.e., $W(F) \geq C|F|^p$ for all $F \in \mathbb{M}^{3 \times 3}$ and some $C > 0$. In order to take into account the important physical properties that the interpenetration of matter does not occur and that an infinite amount of energy is required to compress a finite volume into zero volume, i.e.,

$$W(F) \rightarrow +\infty \text{ as } \det F \rightarrow 0,$$

where $\det F$ denotes the determinant of the 3×3 matrix F , we assume that:

- (C₁) $W(F) = +\infty$ if and only if $\det F \leq 0$;
- (C₂) for every $\delta > 0$, there exists $c_\delta > 0$ such that for all $F \in \mathbb{M}^{3 \times 3}$,
if $\det F \geq \delta$ then $W(F) \leq c_\delta(1 + |F|^p)$.

Our goal is to show that as $\varepsilon \rightarrow 0$ the three-dimensional free energy functional $E_\varepsilon : W^{1,p}(\Sigma_\varepsilon; \mathbb{R}^3) \rightarrow [0, +\infty]$ (with $p > 1$) defined by

$$(1) \quad E_\varepsilon(u) := \frac{1}{\varepsilon} \int_{\Sigma_\varepsilon} W(\nabla u(x, x_3)) dx dx_3$$

converges in a variational sense (see Definition 2.1) to the two-dimensional free energy functional $E_{\text{mem}} : W^{1,p}(\Sigma; \mathbb{R}^3) \rightarrow [0, +\infty]$ given by

$$(2) \quad E_{\text{mem}}(v) := \int_{\Sigma} W_{\text{mem}}(\nabla v(x)) dx$$

with $W_{\text{mem}} : \mathbb{M}^{3 \times 2} \rightarrow [0, +\infty]$. Usually, E_{mem} is called the nonlinear membrane energy associated with the two-dimensional elastic material with respect to the reference configuration Σ . Furthermore we wish to give a representation formula for W_{mem} .

To our knowledge, the problem of giving a variational definition of the nonlinear membrane energy was studied for the first time by Percivale in [17]. His paper

deals with the constraint “ $\det \nabla u > 0$ ” but seems to contain some mistakes. It never was published. Then, in [16] Le Dret and Raoult treated the simpler case where W is of p -polynomial growth, i.e., $W(F) \leq c(1 + |F|^p)$ for all $F \in \mathbb{M}^{3 \times 3}$ and some $c > 0$. Later, in [8, Theorem 1] Ben Belgacem announced to have succeed to handle the constraint “ $\det \nabla u > 0$ ”. In [9], which is the paper corresponding to the note [8], the statement [8, Theorem 1] is partly proved, but a more complete proof can be found in his thesis [7]. Recently, in [4] we gave a variational definition of the nonlinear membrane energy under the constraint “ $\det \nabla u \neq 0$ ”. In the present paper, by the same method as in [4], we obtain the nonlinear membrane energy under the more realistic constraint “ $\det \nabla u > 0$ ”.

An outline of the paper is as follows. The variational convergence of E_ε to E_{mem} as $\varepsilon \rightarrow 0$ as well as a representation formula for W_{mem} are given by Corollary 2.10 in Sect. 2.4. Corollary 2.10 is a consequence of Theorems 2.5, 2.6 and 2.9. Roughly, Theorems 2.5 and 2.6 establish the existence of the variational limit of E_ε as $\varepsilon \rightarrow 0$ (see Sect. 2.2), and Theorem 2.9 gives an integral representation for the corresponding variational limit, and so a representation formula for W_{mem} (see Sect. 2.3).

Theorem 2.5 is proved in Section 4. The principal ingredients are Theorem 2.6 and Theorem 3.4 whose proof (given in Section 3) uses an interchange theorem of infimum and integral that we obtained in [2]. (Note that the techniques used to prove Theorems 2.5 and 3.4 are the same as in [4, Sections 3 and 4].)

Theorem 2.6 is proved in Section 5. The main arguments are two approximation theorems developed by Ben Belgacem-Bennequin (see [7]) and Gromov-Eliashberg (see [14]). These theorems are stated in Appendix A.

Theorem 2.9 is proved in [4, Appendix A] (see also [3]).

2. RESULTS

2.1. Variational convergence. To accomplish our asymptotic analysis, we use the notion of convergence introduced by Anzellotti, Baldo and Percivale in [5] in order to deal with dimension reduction problems in mechanics. Let $\pi = \{\pi_\varepsilon\}_\varepsilon$ be the family of maps $\pi_\varepsilon : W^{1,p}(\Sigma_\varepsilon; \mathbb{R}^3) \rightarrow W^{1,p}(\Sigma; \mathbb{R}^3)$ defined by

$$\pi_\varepsilon(u) := \frac{1}{\varepsilon} \int_{-\frac{\varepsilon}{2}}^{\frac{\varepsilon}{2}} u(\cdot, x_3) dx_3.$$

Definition 2.1. We say that E_ε $\Gamma(\pi)$ -converges to E_{mem} as $\varepsilon \rightarrow 0$, and we write $E_{\text{mem}} = \Gamma(\pi)\text{-}\lim_{\varepsilon \rightarrow 0} E_\varepsilon$, if the following two assertions hold:

(i) for all $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$ and all $\{u_\varepsilon\}_\varepsilon \subset W^{1,p}(\Sigma_\varepsilon; \mathbb{R}^3)$,

$$\text{if } \pi_\varepsilon(u_\varepsilon) \rightarrow v \text{ in } L^p(\Sigma; \mathbb{R}^3) \text{ then } E_{\text{mem}}(v) \leq \liminf_{\varepsilon \rightarrow 0} E_\varepsilon(u_\varepsilon);$$

(ii) for all $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$, there exists $\{u_\varepsilon\}_\varepsilon \subset W^{1,p}(\Sigma_\varepsilon; \mathbb{R}^3)$ such that:

$$\pi_\varepsilon(u_\varepsilon) \rightarrow v \text{ in } L^p(\Sigma; \mathbb{R}^3) \text{ and } E_{\text{mem}}(v) \geq \limsup_{\varepsilon \rightarrow 0} E_\varepsilon(u_\varepsilon).$$

In fact, Definition 2.1 is a variant of De Giorgi’s Γ -convergence. This is made clear by Lemma 2.3. Consider $\mathcal{E}_\varepsilon : W^{1,p}(\Sigma; \mathbb{R}^3) \rightarrow [0, +\infty]$ defined by

$$\mathcal{E}_\varepsilon(v) := \inf \left\{ E_\varepsilon(u) : \pi_\varepsilon(u) = v \right\}.$$

Definition 2.2. We say that \mathcal{E}_ε Γ -converges to E_{mem} as $\varepsilon \rightarrow 0$, and we write $E_{\text{mem}} = \Gamma\text{-lim}_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon$ if for every $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$,

$$\left(\Gamma\text{-lim inf}_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon \right) (v) = \left(\Gamma\text{-lim sup}_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon \right) (v) = E_{\text{mem}}(v),$$

where $(\Gamma\text{-lim inf}_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon)(v) := \inf \{ \liminf_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon(v_\varepsilon) : v_\varepsilon \rightarrow v \text{ in } L^p(\Sigma; \mathbb{R}^3) \}$ and $(\Gamma\text{-lim sup}_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon)(v) := \inf \{ \limsup_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon(v_\varepsilon) : v_\varepsilon \rightarrow v \text{ in } L^p(\Sigma; \mathbb{R}^3) \}$.

For a deeper discussion of the Γ -convergence theory we refer to the book [11]. Clearly, Definition 2.2 is equivalent to assertions (i) and (ii) in definition 2.1 with “ $\pi(u_\varepsilon) \rightarrow v$ ” replaced by “ $v_\varepsilon \rightarrow v$ ”. It is then obvious that

Lemma 2.3. $E_{\text{mem}} = \Gamma(\pi)\text{-lim}_{\varepsilon \rightarrow 0} E_\varepsilon$ if and only if $E_{\text{mem}} = \Gamma\text{-lim}_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon$.

The $\Gamma(\pi)$ -convergence of E_ε in (1) to E_{mem} in (2) as $\varepsilon \rightarrow 0$ as well as a representation formula for W_{mem} are given by Corollary 2.10. It is a consequence of Theorems 2.5, 2.6 and 2.9. Roughly, Theorems 2.5 and 2.6 establish the existence of the $\Gamma(\pi)$ -limit of E_ε as $\varepsilon \rightarrow 0$ (see Sect. 2.2), and Theorem 2.9 gives an integral representation for the corresponding $\Gamma(\pi)$ -limit, and so a representation formula for W_{mem} (see Sect. 2.3).

2.2. Γ -convergence of \mathcal{E}_ε as $\varepsilon \rightarrow 0$. Denote by $C^1(\overline{\Sigma}; \mathbb{R}^3)$ the space of all restrictions to $\overline{\Sigma}$ of C^1 -differentiable functions from \mathbb{R}^2 to \mathbb{R}^3 , and set

$$C_*^1(\overline{\Sigma}; \mathbb{R}^3) := \left\{ v \in C^1(\overline{\Sigma}; \mathbb{R}^3) : \partial_1 v(x) \wedge \partial_2 v(x) \neq 0 \text{ for all } x \in \overline{\Sigma} \right\},$$

where $\partial_1 v(x)$ (resp. $\partial_2 v(x)$) denotes the partial derivative of v at $x = (x_1, x_2)$ with respect to x_1 (resp. x_2). (In fact, $C_*^1(\overline{\Sigma}; \mathbb{R}^3)$ is the set of all C^1 -immersions from $\overline{\Sigma}$ to \mathbb{R}^3 .) Let $\mathcal{E} : W^{1,p}(\Sigma; \mathbb{R}^3) \rightarrow [0, +\infty]$ be defined by

$$\mathcal{E}(v) := \begin{cases} \int_{\Sigma} W_0(\nabla v(x)) dx & \text{if } v \in C_*^1(\overline{\Sigma}; \mathbb{R}^3) \\ +\infty & \text{otherwise,} \end{cases}$$

where $W_0 : \mathbb{M}^{3 \times 2} \rightarrow [0, +\infty]$ is given by

$$W_0(\xi) := \inf_{\zeta \in \mathbb{R}^3} W(\xi \mid \zeta)$$

with $(\xi \mid \zeta)$ denoting the element of $\mathbb{M}^{3 \times 3}$ corresponding to $(\xi, \zeta) \in \mathbb{M}^{3 \times 2} \times \mathbb{R}^3$. (As W is coercive, it is easy to see that W_0 is coercive, i.e., $W_0(\xi) \geq C|\xi|^p$ for all $\xi \in \mathbb{M}^{3 \times 2}$ and some $C > 0$.) The following lemma gives three elementary properties of W_0 (the proof is left to the reader). Note that conditions (C₁) and (C₂) imply W_0 is not of p -polynomial growth.

Lemma 2.4. Denote by $\xi_1 \wedge \xi_2$ the cross product of vectors $\xi_1, \xi_2 \in \mathbb{R}^3$.

- (i) W_0 is continuous.
- (ii) If (C₁) holds then
 - (C₁) $W_0(\xi_1 \mid \xi_2) = +\infty$ if and only if $\xi_1 \wedge \xi_2 = 0$.
- (iii) If (C₂) holds then
 - (C₂) for all $\delta > 0$, there exists $c_\delta > 0$ such that for all $\xi = (\xi_1 \mid \xi_2) \in \mathbb{M}^{3 \times 2}$, if $|\xi_1 \wedge \xi_2| \geq \delta$ then $W_0(\xi) \leq c_\delta(1 + |\xi|^p)$.

Taking Lemma 2.3 into account, we see that the existence of the $\Gamma(\pi)$ -limit of E_ε as $\varepsilon \rightarrow 0$ follows from Theorem 2.5.

Theorem 2.5. *Let assumptions (C_1) and (C_2) hold. Then $\Gamma\text{-}\lim_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon = \bar{\mathcal{E}}$ with $\bar{\mathcal{E}} : W^{1,p}(\Sigma; \mathbb{R}^3) \rightarrow [0, +\infty]$ given by*

$$\bar{\mathcal{E}}(v) := \inf \left\{ \liminf_{n \rightarrow +\infty} \mathcal{E}(v_n) : W^{1,p}(\Sigma; \mathbb{R}^3) \ni v_n \rightarrow v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}.$$

The proof of Theorem 2.5 is established in Section 4. It uses Theorem 3.4 (see Section 3) and Theorem 2.6.

Theorem 2.6. *If (\bar{C}_2) holds then $\bar{\mathcal{E}}(v) = \mathcal{I}(v)$ for all $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$, where $\mathcal{I} : W^{1,p}(\Sigma; \mathbb{R}^3) \rightarrow [0, +\infty]$ is given by*

$$\mathcal{I}(v) := \inf \left\{ \liminf_{n \rightarrow +\infty} \int_{\Sigma} W_0(\nabla v_n(x)) dx : W^{1,p}(\Sigma; \mathbb{R}^3) \ni v_n \rightarrow v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}.$$

Theorem 2.6 is proved in Section 6 by using two approximation theorems developed by Ben Belgacem-Bennequin (see [7]) and Gromov-Eliashberg (see [14]). These theorems are stated in Appendix A.

2.3. Integral representation of \mathcal{I} . From now on, given a bounded open set $D \subset \mathbb{R}^2$ with $|\partial D| = 0$, we denote by $\text{Aff}(D; \mathbb{R}^3)$ the space of all continuous piecewise affine functions from D to \mathbb{R}^3 , i.e., $v \in \text{Aff}(D; \mathbb{R}^3)$ if and only if v is continuous and there exists a finite family $(D_i)_{i \in I}$ of open disjoint subsets of D such that $|\partial D_i| = 0$ for all $i \in I$, $|D \setminus \cup_{i \in I} D_i| = 0$ and for every $i \in I$, $\nabla v(x) = \xi_i$ in D_i with $\xi_i \in \mathbb{M}^{3 \times 2}$ (where $|\cdot|$ denotes the Lebesgue measure in \mathbb{R}^2).

Remark 2.7. In fact $\text{Aff}(\Sigma; \mathbb{R}^3) = \text{Aff}^V(\Sigma; \mathbb{R}^3)$, where $\text{Aff}^V(\Sigma; \mathbb{R}^3)$ is the space of Vitali continuous piecewise affine functions from Σ to \mathbb{R}^3 (introduced by Ben Belgacem in [7, 9]), i.e., $v \in \text{Aff}^V(\Sigma; \mathbb{R}^3)$ if and only if v is continuous and there exists a finite or countable family $(O_i)_{i \in I}$ of disjoint open subsets of Σ such that $|\partial O_i| = 0$ for all $i \in I$, $|\Sigma \setminus \cup_{i \in I} O_i| = 0$, and $v(x) = \xi_i \cdot x + a_i$ if $x \in O_i$, where $a_i \in \mathbb{R}^3$, $\xi_i \in \mathbb{M}^{3 \times 2}$ and $\text{Card}\{\xi_i : i \in I\}$ is finite. Indeed, setting $D_i := \{x \in \cup_{i \in I} O_i : \nabla v(x) = \xi_i\}$ with $v \in \text{Aff}^V(\Sigma; \mathbb{R}^3)$, we see that $\text{Card}\{D_i : i \in I\}$ is finite. Thus $\text{Aff}^V(\Sigma; \mathbb{R}^3) \subset \text{Aff}(\Sigma; \mathbb{R}^3)$. Given $v \in \text{Aff}(\Sigma; \mathbb{R}^3)$, let $(O_j)_{j \in J_i}$ be the connected components of D_i with $i \in I$ (where I is finite). Since D_i is open, O_j is open for all $j \in J_i$, hence J_i is finite or countable because \mathbb{Q}^2 is dense in \mathbb{R}^2 . Moreover, for each $j \in J_i$, the restriction of v to O_j is affine. Thus $\text{Aff}(\Sigma; \mathbb{R}^3) \subset \text{Aff}^V(\Sigma; \mathbb{R}^3)$.

Define $\mathcal{Z}W_0 : \mathbb{M}^{3 \times 2} \rightarrow [0, +\infty]$ by

$$(3) \quad \mathcal{Z}W_0(\xi) := \inf \left\{ \int_Y W_0(\xi + \nabla \phi(y)) dy : \phi \in \text{Aff}_0(Y; \mathbb{R}^3) \right\}$$

where $Y :=]0, 1[$ and $\text{Aff}_0(Y; \mathbb{R}^3) := \{\phi \in \text{Aff}(Y; \mathbb{R}^3) : \phi = 0 \text{ on } \partial Y\}$. (As W_0 is coercive, it is easy to see that $\mathcal{Z}W_0$ is coercive.) Recall the definitions of quasiconvexity and quasiconvex envelope:

Definition 2.8. Let $f : \mathbb{M}^{3 \times 2} \rightarrow [0, +\infty]$ be a Borel measurable function.

- (i) We say that f is quasiconvex if for every $\xi \in \mathbb{M}^{3 \times 2}$, every bounded open set $D \subset \mathbb{R}^2$ with $|\partial D| = 0$ and every $\phi \in W_0^{1,\infty}(D; \mathbb{R}^3)$,

$$f(\xi) \leq \frac{1}{|D|} \int_D f(\xi + \nabla \phi(x)) dx.$$

- (ii) By the quasiconvex envelope of f , we mean the unique function (when it exists) $\mathcal{Q}f : \mathbb{M}^{3 \times 2} \rightarrow [0, +\infty]$ such that:
- $\mathcal{Q}f$ is Borel measurable, quasiconvex and $\mathcal{Q}f \leq f$;
 - for all $g : \mathbb{M}^{3 \times 2} \rightarrow [0, +\infty]$, if g is Borel measurable, quasiconvex and $g \leq f$, then $g \leq \mathcal{Q}f$.
- (Usually, for simplicity, we say that $\mathcal{Q}f$ is the greatest quasiconvex function which less than or equal to f .)

Under (\overline{C}_2) , we proved that $\mathcal{Z}W_0$ is of p -polynomial growth and so continuous (see [4, Propositions A.3 and A.1(iii)]) and that $\mathcal{Z}W_0$ is the quasiconvex envelope of W_0 , i.e., $\mathcal{Z}W_0 = \mathcal{Q}W_0$ (see [4, Proposition A.5]). Taking Theorems 2.5 and 2.6 together with Lemmas 2.3 and 2.4(iii) into account, we see that Theorem 2.9 gives an integral representation for the $\Gamma(\pi)$ -limit of E_ε as $\varepsilon \rightarrow 0$ as well as a representation formula for W_{mem} .

Theorem 2.9. *If (\overline{C}_2) holds then for every $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$,*

$$\mathcal{I}(v) = \int_{\Sigma} \mathcal{Q}W_0(\nabla v(x)) dx.$$

Theorem 2.9 is proved in [4, Appendix A] (see also [3]).

2.4. $\Gamma(\pi)$ -convergence of E_ε to E_{mem} as $\varepsilon \rightarrow 0$. According to Lemmas 2.3 and Lemma 2.4(iii), a direct consequence of Theorems 2.5, 2.6 and 2.9 is the following.

Corollary 2.10. *Let assumptions (C_1) and (C_2) hold. Then as $\varepsilon \rightarrow 0$, E_ε in (1) $\Gamma(\pi)$ -converge to E_{mem} in (2) with $W_{\text{mem}} = \mathcal{Q}W_0$.*

Remark 2.11. Corollary 2.10 can be applied when $W : \mathbb{M}^{3 \times 3} \rightarrow [0, +\infty]$ is given by

$$W(F) := h(\det F) + |F|^p,$$

where $h : \mathbb{R} \rightarrow [0, +\infty]$ is a continuous function such that:

- $h(t) = +\infty$ if and only if $t \leq 0$;
- for every $\delta > 0$, there exists $r_\delta > 0$ such that $h(t) \leq r_\delta$ for all $t \geq \delta$.

3. REPRESENTATION OF \mathcal{E}

The goal of this section is to show Theorem 3.4. To this end, we begin by proving two lemmas.

For every $v \in C_*^1(\overline{\Sigma}; \mathbb{R}^3)$ and $j \geq 1$, we define the multifunction $\Lambda_v^j : \overline{\Sigma} \rightrightarrows \mathbb{R}^3$ by

$$\Lambda_v^j(x) := \left\{ \zeta \in \mathbb{R}^3 : \det(\nabla v(x) \mid \zeta) \geq \frac{1}{j} \right\}.$$

Lemma 3.1. *Let $v \in C_*^1(\overline{\Sigma}; \mathbb{R}^3)$. Then:*

- (i) for every $j \geq 1$, Λ_v^j is a nonempty convex closed-valued lower semicontinuous¹ multifunction;
- (ii) for every $x \in \overline{\Sigma}$, $\Lambda_v^1(x) \subset \cdots \subset \Lambda_v^j(x) \subset \cdots \subset \cup_{j \geq 1} \Lambda_v^j(x) = \Lambda_v(x)$, where $\Lambda_v(x) := \{\zeta \in \mathbb{R}^3 : \det(\nabla v(x) \mid \zeta) > 0\}$.

¹A multifunction $\Lambda : \overline{\Sigma} \rightarrow \mathbb{R}^3$ is said to be lower semicontinuous if for every closed subset X of \mathbb{R}^3 , every $x \in \overline{\Sigma}$ and every $\{x_n\}_{n \geq 1} \subset \overline{\Sigma}$ such that $|x_n - x| \rightarrow 0$ as $n \rightarrow +\infty$ and $\Lambda(x_n) \subset X$ for all $n \geq 1$, we have $\Lambda(x) \subset X$ (see [6] for more details).

Proof. (ii) is obvious. Prove then (i). Let $j \geq 1$. It is easy to see that for every $x \in \overline{\Sigma}$, $\Lambda_v^j(x)$ is nonempty, convex and closed. Let X be a closed subset of \mathbb{R}^3 , let $x \in \overline{\Sigma}$, and let $\{x_n\}_{n \geq 1} \subset \overline{\Sigma}$ such that $|x_n - x| \rightarrow 0$ as $n \rightarrow +\infty$ and $\Lambda_v^j(x_n) \subset X$ for all $n \geq 1$. Let $\zeta \in \Lambda_v^j(x)$ and let $\{\zeta_m\}_{m \geq 1} \subset \mathbb{R}^3$ be given by $\zeta_m := \zeta + \frac{1}{m}\zeta$. Then, for every $m \geq 1$,

$$(4) \quad \det(\nabla v(x) \mid \zeta_m) = \det(\nabla v(x) \mid \zeta) + \frac{1}{m} \det(\nabla v(x) \mid \zeta) \geq \frac{1}{j} + \frac{1}{mj}.$$

Fix any $m \geq 1$. Since $\det(\nabla v(x_n) \mid \zeta_m) \rightarrow \det(\nabla v(x) \mid \zeta_m)$ as $n \rightarrow +\infty$, using (4) we see that $\det(\nabla v(x_{n_0}) \mid \zeta_m) > \frac{1}{j}$ for some $n_0 \geq 1$, so that $\zeta_m \in \Lambda_v^j(x_{n_0})$. Thus $\zeta_m \in X$ for all $m \geq 1$. As X is closed we have $\zeta = \lim_{m \rightarrow +\infty} \zeta_m \in X$. \square

In the sequel, given $\Lambda : \overline{\Sigma} \rightrightarrows \mathbb{R}^3$ we set

$$C(\overline{\Sigma}; \Lambda) := \left\{ \phi \in C(\overline{\Sigma}; \mathbb{R}^3) : \phi(x) \in \Lambda(x) \text{ for all } x \in \overline{\Sigma} \right\},$$

where $C(\overline{\Sigma}; \mathbb{R}^3)$ denotes the space of all continuous functions from $\overline{\Sigma}$ to \mathbb{R}^3 .

Lemma 3.2. *Given $v \in C_*^1(\Sigma; \mathbb{R}^3)$ and $j \geq 1$, if (C_2) holds, then*

$$\inf_{\phi \in C(\overline{\Sigma}; \Lambda_v^j)} \int_{\Sigma} W(\nabla v(x) \mid \phi(x)) dx = \int_{\Sigma} \inf_{\zeta \in \Lambda_v^j(x)} W(\nabla v(x) \mid \zeta) dx.$$

To prove Lemma 3.2 we need the following interchange theorem of infimum and integral (that we proved in [2, Corollary 5.4]).

Theorem 3.3. *Let $\Gamma : \overline{\Sigma} \rightrightarrows \mathbb{R}^3$ and let $f : \overline{\Sigma} \times \mathbb{R}^3 \rightarrow [0, +\infty]$. Assume that:*

- (H₁) *f is a Carathéodory integrand;*
- (H₂) *Γ is a nonempty convex closed-valued lower semicontinuous multifunction;*
- (H₃) *$C(\overline{\Sigma}; \Gamma) \neq \emptyset$ and for every $\phi, \hat{\phi} \in C(\overline{\Sigma}; \Gamma)$,*

$$\int_{\Sigma} \max_{\alpha \in [0,1]} f(x, \alpha\phi(x) + (1-\alpha)\hat{\phi}(x)) dx < +\infty.$$

Then,

$$\inf_{\phi \in C(\overline{\Sigma}; \Gamma)} \int_{\Sigma} f(x, \phi(x)) dx = \int_{\Sigma} \inf_{\zeta \in \Gamma(x)} f(x, \zeta) dx.$$

Proof of Lemma 3.2. Since W is continuous, (H₁) holds with $f(x, \zeta) = W(\nabla v(x) \mid \zeta)$. Lemma 3.1 shows that (H₂) is satisfied with $\Gamma = \Lambda_v^j$, and $C(\overline{\Sigma}; \Lambda_v^j) \neq \emptyset$ (for example $\Phi : \overline{\Sigma} \rightarrow \mathbb{R}^3$ defined by (8) belongs to $C(\overline{\Sigma}; \Lambda_v^j)$). Given $\phi, \hat{\phi} \in C(\overline{\Sigma}; \Lambda_v^j)$, it is clear that $\det(\nabla v(x) \mid \alpha\phi(x) + (1-\alpha)\hat{\phi}(x)) \geq 1/j$ for all $\alpha \in [0, 1]$ and all $x \in \overline{\Sigma}$. From (C₂) it follows that there exists $c > 0$ depending only on j, v, ϕ and $\hat{\phi}$ such that $W(\nabla v(x) \mid \alpha\phi(x) + (1-\alpha)\hat{\phi}(x)) \leq c$ for all $x \in \overline{\Sigma}$. Thus (H₃) is verified with $f(x, \zeta) = W(\nabla v(x) \mid \zeta)$ and $\Gamma = \Lambda_v^j$, and Lemma 3.2 follows from Lemma 3.3. \square

Here is our (non integral) representation theorem for \mathcal{E} .

Theorem 3.4. *If (C₁) and (C₂) hold, then for every $v \in C_*^1(\overline{\Sigma}; \mathbb{R}^3)$,*

$$(5) \quad \mathcal{E}(v) = \inf_{j \geq 1} \inf_{\phi \in C(\overline{\Sigma}; \Lambda_v^j)} \int_{\Sigma} W(\nabla v(x) \mid \phi(x)) dx.$$

Proof. Fix $v \in C_*^1(\overline{\Sigma}; \mathbb{R}^3)$ and denote by $\hat{\mathcal{E}}(v)$ the right-hand side of (5). It is easy to verify that $\mathcal{E}(v) \leq \hat{\mathcal{E}}(v)$. We are thus reduced to prove that

$$(6) \quad \hat{\mathcal{E}}(v) \leq \mathcal{E}(v).$$

Using Lemma 3.2, we obtain

$$(7) \quad \hat{\mathcal{E}}(v) \leq \inf_{j \geq 1} \int_{\Sigma} \inf_{\zeta \in \Lambda_v^j(x)} W(\nabla v(x) \mid \zeta) dx.$$

Consider the continuous function $\Phi : \overline{\Sigma} \rightarrow \mathbb{R}^3$ defined by

$$(8) \quad \Phi(x) := \frac{\partial_1 v(x) \wedge \partial_2 v(x)}{|\partial_1 v(x) \wedge \partial_2 v(x)|^2}.$$

Then, $\det(\nabla v(x) \mid \Phi(x)) = 1$ for all $x \in \overline{\Sigma}$. Using (C₂) we deduce that there exists $c > 0$ depending only on p such that

$$\int_{\Sigma} \inf_{\zeta \in \Lambda_v^1(x)} W(\nabla v(x) \mid \zeta) dx \leq c(|\Sigma| + \|\nabla v\|_{L^p(\Sigma; \mathbb{M}^{3 \times 2})}^p + \|\Phi\|_{L^p(\Sigma; \mathbb{R}^3)}^p).$$

It follows that $\inf_{\zeta \in \Lambda_v^1(\cdot)} W(\nabla v(\cdot) \mid \zeta) \in L^1(\Sigma)$. From Lemma 3.1(i) and (ii), we see that $\{\inf_{\zeta \in \Lambda_v^j(\cdot)} W(\nabla v(\cdot) \mid \zeta)\}_{j \geq 1}$ is non-increasing, and that for every $x \in \overline{\Sigma}$,

$$(9) \quad \inf_{j \geq 1} \inf_{\zeta \in \Lambda_v^j(x)} W(\nabla v(x) \mid \zeta) = W_0(\nabla v(x)),$$

and (19) follows from (7) and (9) by using Lebesgue's dominated convergence theorem. \square

4. PROOF OF THEOREM 2.5

In this section we prove Theorem 2.5. Since $\Gamma\text{-}\liminf_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon \leq \Gamma\text{-}\limsup_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon$, we only need to show that:

- (a) $\overline{\mathcal{E}} \leq \Gamma\text{-}\liminf_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon$;
- (b) $\Gamma\text{-}\limsup_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon \leq \overline{\mathcal{E}}$.

In the sequel, we follow the notation used in Section 3.

4.1. Proof of (a). Let $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$ and let $\{v_\varepsilon\}_\varepsilon \subset W^{1,p}(\Sigma; \mathbb{R}^3)$ be such that $v_\varepsilon \rightarrow v$ in $L^p(\Sigma; \mathbb{R}^3)$. We have to prove that

$$(10) \quad \liminf_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon(v_\varepsilon) \geq \overline{\mathcal{E}}(v).$$

Without loss of generality we can assume that $\sup_{\varepsilon > 0} \mathcal{E}_\varepsilon(v_\varepsilon) < +\infty$. To every $\varepsilon > 0$ there corresponds $u_\varepsilon \in \pi_\varepsilon^{-1}(v_\varepsilon)$ such that

$$(11) \quad \mathcal{E}_\varepsilon(v_\varepsilon) \geq E_\varepsilon(u_\varepsilon) - \varepsilon.$$

Defining $\hat{u}_\varepsilon : \Sigma_1 \rightarrow \mathbb{R}^3$ by $\hat{u}_\varepsilon(x, x_3) := u_\varepsilon(x, \varepsilon x_3)$ we have

$$(12) \quad E_\varepsilon(u_\varepsilon) = \int_{\Sigma_1} W\left(\partial_1 \hat{u}_\varepsilon(x, x_3) \mid \partial_2 \hat{u}_\varepsilon(x, x_3) \mid \frac{1}{\varepsilon} \partial_3 \hat{u}_\varepsilon(x, x_3)\right) dx dx_3.$$

Using the coercivity of W , we deduce that $\|\partial_3 \hat{u}_\varepsilon\|_{L^p(\Sigma_1; \mathbb{R}^3)} \leq c\varepsilon^p$ for all $\varepsilon > 0$ and some $c > 0$, and so $\|\hat{u}_\varepsilon - v_\varepsilon\|_{L^p(\Sigma_1; \mathbb{R}^3)} \leq c'\varepsilon^p$ by Poincaré-Wirtinger's inequality, where $c' > 0$ is a constant which does not depend on ε . It follows that $\hat{u}_\varepsilon \rightarrow v$ in $L^p(\Sigma_1; \mathbb{R}^3)$. For $x_3 \in]-\frac{1}{2}, \frac{1}{2}[$, let $w_\varepsilon^{x_3} \in W^{1,p}(\Sigma; \mathbb{R}^3)$ given by $w_\varepsilon^{x_3}(x) := \hat{u}_\varepsilon(x, x_3)$.

Then (up to a subsequence) $w_\varepsilon^{x_3} \rightarrow v$ in $L^p(\Sigma; \mathbb{R}^3)$ for a.e. $x_3 \in]-\frac{1}{2}, \frac{1}{2}[$. Taking (11) and (12) into account and using Fatou's lemma, we obtain

$$\liminf_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon(v_\varepsilon) \geq \int_{-\frac{1}{2}}^{\frac{1}{2}} \left(\liminf_{\varepsilon \rightarrow 0} \int_\Sigma W_0(\nabla w_\varepsilon^{x_3}(x)) dx \right) dx_3,$$

and so $\liminf_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon(v_\varepsilon) \geq \mathcal{I}(v)$, and (10) follows by using Theorem 2.6. \square

4.2. Proof of (b). As Γ -lim sup $\varepsilon \rightarrow 0$ \mathcal{E}_ε is lower semicontinuous with respect to the strong topology of $L^p(\Sigma; \mathbb{R}^3)$ (see [11, Proposition 6.8 p. 57]), it is sufficient to prove that for every $v \in C_*^1(\overline{\Sigma}; \mathbb{R}^3)$,

$$(13) \quad \limsup_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon(v) \leq \mathcal{E}(v).$$

Given $v \in C_*^1(\overline{\Sigma}; \mathbb{R}^3)$, fix any $j \geq 1$, and any $n \geq 1$. Using Theorem 3.4 we obtain the existence of $\phi \in C(\overline{\Sigma}; \Lambda_v^j)$ such that

$$(14) \quad \int_\Sigma W(\nabla v(x) \mid \phi(x)) dx \leq \mathcal{E}(v) + \frac{1}{n}.$$

By Stone-Weierstrass's approximation theorem, there exists $\{\phi_k\}_{k \geq 1} \subset C^\infty(\overline{\Sigma}; \mathbb{R}^3)$ such that

$$(15) \quad \phi_k \rightarrow \phi \text{ uniformly as } k \rightarrow +\infty.$$

We claim that:

$$(c_1) \quad \det(\nabla v(x) \mid \phi_k(x)) \geq \frac{1}{2j} \text{ for all } x \in \overline{\Sigma}, \text{ all } k \geq k_v \text{ and some } k_v \geq 1;$$

$$(c_2) \quad \lim_{k \rightarrow +\infty} \int_\Sigma W(\nabla v(x) \mid \phi_k(x)) dx = \int_\Sigma W(\nabla v(x) \mid \phi(x)) dx.$$

Indeed, setting $\mu_v := \sup_{x \in \overline{\Sigma}} |\partial_1 v(x) \wedge \partial_2 v(x)|$ ($\mu_v > 0$) and using (15), we deduce that there exists $k_v \geq 1$ such that for every $k \geq k_v$,

$$(16) \quad \sup_{x \in \overline{\Sigma}} |\phi_k(x) - \phi(x)| < \frac{1}{2j\mu_v}.$$

Let $x \in \overline{\Sigma}$, and let $k \geq k_v$. As $\phi \in C(\overline{\Sigma}; \Lambda_v^j)$ we have

$$(17) \quad \det(\nabla v(x) \mid \phi_k(x)) \geq \frac{1}{j} - \det(\nabla v(x) \mid \phi_k(x) - \phi(x)).$$

Noticing that $\det(\nabla v(x) \mid \phi_k(x) - \phi(x)) \leq |\partial_1 v(x) \wedge \partial_2 v(x)| |\phi_k(x) - \phi(x)|$, from (16) and (17) we deduce that $\det(\nabla v(x) \mid \phi_k(x)) \geq \frac{1}{2j}$, and (c₁) is proved. Combining (c₁) with (C₂) we see that $\sup_{k \geq k_v} W(\nabla v(\cdot) \mid \phi_k(\cdot)) \in L^1(\Sigma)$. As W is continuous we have $\lim_{k \rightarrow +\infty} W(\nabla v(x) \mid \phi_k(x)) = W(\nabla v(x) \mid \phi(x))$ for all $x \in V$, and (c₂) follows by using Lebesgue's dominated convergence theorem, which completes the claim.

Fix any $k \geq k_v$ and define $\theta :]-\frac{1}{2}, \frac{1}{2}[\rightarrow \mathbb{R}$ by $\theta(x_3) := \inf_{x \in \overline{\Sigma}} \det(\nabla v(x) + x_3 \nabla \phi_k(x) \mid \phi_k(x))$. Clearly θ is continuous. By (c₁) we have $\theta(0) \geq \frac{1}{2j}$, and so there exists $\eta_v \in]0, \frac{1}{2}[$ such that $\theta(x_3) \geq \frac{1}{4j}$ for all $x_3 \in]-\eta_v, \eta_v[$. Let $u_k : \Sigma_1 \rightarrow \mathbb{R}$ be given by $u_k(x, x_3) := v(x) + x_3 \phi_k(x)$. From the above it follows that

$$(c_3) \quad \det \nabla u_k(x, \varepsilon x_3) \geq \frac{1}{4j} \text{ for all } \varepsilon \in]0, \eta_v[\text{ and all } (x, x_3) \in \overline{\Sigma} \times]-\frac{1}{2}, \frac{1}{2}[.$$

As in the proof of (c₁), from (c₃) together with (C₂) and the continuity of W , we obtain

$$(18) \quad \lim_{\varepsilon \rightarrow 0} E_\varepsilon(u_k) = \lim_{\varepsilon \rightarrow 0} \int_{\Sigma_1} W(\nabla u_k(x, \varepsilon x_3)) dx dx_3 = \int_{\Sigma} W(\nabla v(x) \mid \phi_k(x)) dx.$$

For every $\varepsilon > 0$ and every $k \geq k_v$, since $\pi_\varepsilon(u_k) = v$ we have $\mathcal{E}_\varepsilon(v) \leq E_\varepsilon(u_k)$. Using (18), (c₂) and (14), we deduce that

$$\limsup_{\varepsilon \rightarrow 0} \mathcal{E}_\varepsilon(v) \leq \mathcal{E}(v) + \frac{1}{n},$$

and (13) follows by letting $n \rightarrow +\infty$. \square

5. PROOF OF THEOREM 2.6

In this section, we prove of Theorem 2.6. It is based upon two approximation theorems by Ben Belgacem-Bennequin (see Sect. A.1) and Gromov-Eliasberg (see Sect. A.2).

Recall the definition of rank one convexity and rank one convex envelope:

Definition 5.1. Let $f : \mathbb{M}^{3 \times 2} \rightarrow [0, +\infty]$ be a Borel measurable function.

- (i) We say that f is rank one convex if for every $\alpha \in]0, 1[$ and every $\xi, \xi' \in \mathbb{M}^{3 \times 2}$ with $\text{rank}(\xi - \xi') = 1$,

$$f(\alpha \xi + (1 - \alpha)\xi') \leq \alpha f(\xi) + (1 - \alpha)f(\xi').$$

- (ii) By the rank one convex envelope of f , that we denote by $\mathcal{R}f$, we mean the greatest rank one convex function which less than or equal to f .

In [7, Proposition 7 p. 32 and Lemma 8 p. 34] (see also [9, Sect. 5.1], [18, Proposition 3.4.4 p. 112] and [19, Lemma 6.5]) Ben Belgacem proved the following lemma that we will use in the proof of Theorem 2.6. (As W_0 is coercive, it is easy to see that $\mathcal{R}W_0$ is coercive.)

Lemma 5.2. *If (\overline{C}_2) holds then:*

- (i) $\mathcal{R}W_0(\xi) \leq c(1 + |\xi|^p)$ for all $\xi \in \mathbb{M}^{3 \times 2}$ and some $c > 0$;
(ii) $\mathcal{R}W_0$ is continuous.

Define $I : W^{1,p}(\Sigma; \mathbb{R}^3) \rightarrow [0, +\infty]$ by

$$I(v) := \inf \left\{ \liminf_{n \rightarrow +\infty} \int_{\Sigma} W_0(\nabla v_n(x)) dx : \text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3) \ni v_n \rightarrow v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}$$

with $\text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3) := \{v \in \text{Aff}^{ET}(\Sigma; \mathbb{R}^3) : v \text{ is locally injective}\}$ ($\text{Aff}^{ET}(\Sigma; \mathbb{R}^3)$ is defined in Sect. A.1). To prove Theorem 2.6 we will use Proposition 5.3.

Proposition 5.3. $I = J$ with $J : W^{1,p}(\Sigma; \mathbb{R}^3) \rightarrow [0, +\infty]$ given by

$$J(v) := \inf \left\{ \liminf_{n \rightarrow +\infty} \int_{\Sigma} \mathcal{R}W_0(\nabla v_n(x)) dx : \text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3) \ni v_n \rightarrow v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}.$$

To prove Proposition 5.3 we need Lemma 5.4 whose proof is contained in the thesis² of Ben Belgacem [7].

²Since it is difficult to lay hands on this thesis (which is written in French), in the next version of our paper we will add the proof of Lemma 5.4 in appendix.

Lemma 5.4. *If $v \in \text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3)$ then*

$$I(v) \leq \int_{\Sigma} \mathcal{R}W_0(\nabla v(x)) dx.$$

Proof of Proposition 5.3. Clearly $J \leq I$. We are thus reduced to prove that

$$(19) \quad I \leq J.$$

Fix any $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$ and any sequence $v_n \rightarrow v$ in $L^p(\Sigma; \mathbb{R}^3)$ with $v_n \in \text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3)$. Using Lemma 5.4 we have $I(v_n) \leq \int_{\Sigma} \mathcal{R}W_0(\nabla v_n(x)) dx$ for all $n \geq 1$. Thus,

$$I(v) \leq \liminf_{n \rightarrow +\infty} I(v_n) \leq \liminf_{n \rightarrow +\infty} \int_{\Sigma} \mathcal{R}W_0(\nabla v_n(x)) dx,$$

and (19) follows. \square

Proof of Theorem 2.6. We first prove that

$$(20) \quad \bar{\mathcal{E}} \leq I.$$

As in the proof of Proposition 5.3, it suffices to show that if $v \in \text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3)$ then

$$(21) \quad \bar{\mathcal{E}}(v) \leq \int_{\Sigma} W_0(\nabla v(x)) dx.$$

Let $v \in \text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3)$. By Theorem A.1, there exists $\{v_n\}_{n \geq 1} \subset C_*^1(\bar{\Sigma}; \mathbb{R}^3)$ such that (A₁) and (A₂) holds and $\nabla v_n(x) \rightarrow \nabla v(x)$ a.e. in Σ . As W_0 is continuous (see Lemma 2.4(i)), we have

$$\lim_{n \rightarrow +\infty} W_0(\nabla v_n(x)) = W_0(\nabla v(x)) \quad \text{a.e. in } \Sigma.$$

Using (\bar{C}_2) together with (A₂), we deduce that there exists $c > 0$ such that for every $n \geq 1$ and every measurable set $A \subset \Sigma$,

$$\int_A W_0(\nabla v_n(x)) dx \leq c \left(|A| + \int_A |\nabla v_n(x) - \nabla v(x)|^p dx + \int_A |\nabla v(x)|^p dx \right).$$

But $\nabla v_n \rightarrow \nabla v$ in $L^p(\Sigma; \mathbb{M}^{3 \times 2})$ by (A₁), hence $\{W_0(\nabla v_n(\cdot))\}_{n \geq 1}$ is absolutely uniformly integrable. Using Vitali's theorem, we obtain

$$\lim_{n \rightarrow +\infty} \int_{\Sigma} W_0(\nabla v_n(x)) dx = \int_{\Sigma} W_0(\nabla v(x)) dx,$$

and (21) follows.

We now prove that

$$(22) \quad J \leq \bar{J},$$

with $\bar{J} : W^{1,p}(\Sigma; \mathbb{R}^3) \rightarrow [0, +\infty]$ given by

$$\bar{J}(v) := \inf \left\{ \liminf_{n \rightarrow +\infty} \int_{\Sigma} \mathcal{R}W_0(\nabla v_n(x)) dx : W^{1,p}(\Sigma; \mathbb{R}^3) \ni v_n \rightarrow v \text{ in } L^p(\Sigma; \mathbb{R}^3) \right\}.$$

It is sufficient to show that

$$(23) \quad J(v) \leq \int_{\Sigma} \mathcal{R}W_0(\nabla v(x)) dx.$$

Let $v \in W^{1,p}(\Sigma; \mathbb{R}^3)$. By Corollary A.5, there exists $\{v_n\}_{n \geq 1} \subset \text{Aff}_{\text{li}}(\Sigma; \mathbb{R}^3)$ such that $\nabla v_n \rightarrow \nabla v$ in $L^p(\Sigma; \mathbb{R}^3)$ and $\nabla v_n(x) \rightarrow \nabla v(x)$ a.e. in Σ . Taking Lemma 5.2 into account, from Vitali's lemma, we see that

$$\lim_{n \rightarrow +\infty} \int_{\Sigma} \mathcal{R}W_0(\nabla v_n(x)) dx = \int_{\Sigma} \mathcal{R}W_0(\nabla v(x)) dx,$$

and (23) follows.

Noticing that $\mathcal{I} \leq \overline{\mathcal{E}}$ and $\overline{\mathcal{J}} \leq \mathcal{I}$, and combining Proposition 5.3 with (20) and (22), we conclude that $\overline{\mathcal{E}} = \mathcal{I}$. \square

APPENDIX A. APPROXIMATION THEOREMS

A.1. Ben Belgacem-Bennequin's theorem. Denote by $\text{Aff}^{ET}(\Sigma; \mathbb{R}^3)$ the space of Ekeland-Temam continuous piecewise affine functions from Σ to \mathbb{R}^3 , i.e., $u \in \text{Aff}^{ET}(\Sigma; \mathbb{R}^3)$ if and only if v is continuous and there exists a finite family $(V_i)_{i \in I}$ of open disjoint subsets of Σ such that $|\Sigma \setminus \cup_{i \in I} V_i| = 0$ and for every $i \in I$, the restriction of v to V_i is affine. Note that from Ekeland-Temam [12], we know that $\text{Aff}^{ET}(\Sigma; \mathbb{R}^3)$ is strongly dense in $W^{1,p}(\Sigma; \mathbb{R}^3)$. Set

$$\text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3) := \left\{ v \in \text{Aff}^{ET}(\Sigma; \mathbb{R}^3) : v \text{ is locally injective} \right\}.$$

In [7, Lemma 8 p. 114] (see also [18, Proposition C.0.4 p. 127] and [19, Lemma 1.3]) Ben Belgacem and Bennequin proved the following result.

Theorem A.1. *For every $v \in \text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3)$, there exists $\{v_n\}_{n \geq 1} \subset C_*^1(\overline{\Sigma}; \mathbb{R}^3)$ such that:*

- (A₁) $v_n \rightarrow v$ in $W^{1,p}(\Sigma; \mathbb{R}^3)$;
- (A₂) there exists $\delta > 0$ such that $|\partial_1 v_n(x) \wedge \partial_2 v_n(x)| \geq \delta$ for all $x \in \overline{\Sigma}$ and all $n \geq 1$.

A.2. Gromov-Eliashberg's theorem. In [14, Theorem 1.3.4B] (see also [15, Theorem B'₁ p. 20]) Gromov and Eliashberg proved the following result.

Theorem A.2. *Let $1 \leq N < m$ be two integers and let M be a compact N -dimensional manifold which can be immersed in \mathbb{R}^m . Then, for each C^1 -differentiable function v from M to \mathbb{R}^m there exists a sequence $\{v_n\}_n$ of C^1 -immersions from M to \mathbb{R}^m such that $v_n \rightarrow v$ in $W^{1,p}(M; \mathbb{R}^m)$.*

In our context, we have

Theorem A.3. *For every $v \in C^1(\overline{\Sigma}; \mathbb{R}^3)$ there exists $\{v_n\}_{n \geq 1} \subset C_*^1(\overline{\Sigma}; \mathbb{R}^3)$ such that $v_n \rightarrow v$ in $W^{1,p}(\Sigma; \mathbb{R}^3)$.*

Moreover, from [18, Proposition 3.1.7 p. 100], we have

Proposition A.4. *For every $v \in C_*^1(\overline{\Sigma}; \mathbb{R}^3)$ there exists $\{v_n\}_{n \geq 1} \subset \text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3)$ such that $v_n \rightarrow v$ in $W^{1,p}(\Sigma; \mathbb{R}^3)$.*

Thus, as a consequence of Theorem A.3 and Proposition A.4, we obtain

Corollary A.5. *$\text{Aff}_{\text{li}}^{ET}(\Sigma; \mathbb{R}^3)$ is strongly dense in $W^{1,p}(\Sigma; \mathbb{R}^3)$.*

REFERENCES

- [1] ACERBI, E., BUTTAZZO, G., PERCIVALE, D.: A variational definition for the strain energy of an elastic string, *J. Elasticity* **25**, 137-148 (1991)
- [2] ANZA HAFSA, O., MANDALLENA, J.-P.: Interchange of infimum and integral, *Calc. Var. Partial Differential Equations* **18**, 433-449 (2003)
- [3] ANZA HAFSA, O., MANDALLENA, J.-P.: Relaxation of variational problems in two-dimensional nonlinear elasticity, to appear on *Ann. Mat. Pura Appl.*
- [4] ANZA HAFSA, O., MANDALLENA, J.-P.: The nonlinear membrane energy: variational derivation under the constraint “ $\det \nabla u \neq 0$ ”, to appear on *J. Math. Pures Appl.*
- [5] ANZELLOTTI, G., BALDO, S., PERCIVALE, D.: Dimension reduction in variational problems, asymptotic development in Γ -convergence and thin elastic structures in elasticity, *Asymptot. Anal.* **9**, 61-100 (1994)
- [6] AUBIN, J.-P., FRANKOWSKA, H.: *Set-valued analysis*, Birkäuser, Boston (1990)
- [7] BEN BELGACEM, H: Modélisation de structures minces en élasticité non linéaire, Thèse de Doctorat, Université Pierre et Marie Curie, (1996)
- [8] BEN BELGACEM, H: Une méthode de Γ -convergence pour un modèle de membrane non linéaire, *C. R. Acad. Sci. Paris Série I* **323**, 845-849 (1996)
- [9] BEN BELGACEM, H: Relaxation of singular functionals defined on Sobolev spaces, *ESAIM: COCV* **5** 71-85 (2000)
- [10] DACOROGNA, B.: *Direct Methods in the Calculus of Variations*, Springer-Verlag, Berlin (1989)
- [11] DAL MASO, G.: *An introduction to Γ -convergence*, Birkäuser, Boston (1993)
- [12] EKELAND, I., TEMAM, R.: *Analyse convexe et problèmes variationnels*, Dunod, Gauthier Villars, Paris (1974)
- [13] FONSECA, I.: The lower quasiconvex envelope of the stored energy function for an elastic crystal, *J. Math. Pures et Appl.* **67**, 175-195 (1988)
- [14] GROMOV, M. L., ELIASHBERG, JA. M.: Construction of nonsingular isoperimetric films, *Trudy Mat. Inst. Steklov* **116**, 18-33 (1971). Translated in Proc. Steklov Inst. Math. **116**, 13-28 (1971)
- [15] GROMOV, M. L.: *Partial differential relations*, Springer-Verlag, Berlin (1986)
- [16] LE DRET, H., RAOULT, A.: The nonlinear membrane model as variational limit of nonlinear three-dimensional elasticity, *J. Math. Pures Appl.* **74**, 549-578 (1995)
- [17] PERCIVALE, D.: The variational method for tensile structures, preprint n°16, Dipartimento di Matematica Politecnico di Torino (1991)
- [18] TRABELSI, K.: Sur la modélisation des plaques minces en élasticité non linéaire, Thèse de Doctorat, Université Pierre et Marie Curie, (2004)
- [19] TRABELSI, K.: Modeling of a membrane plate model for incompressible materials via Gamma-convergence, to appear on *Anal. Appl.* (Singap.)

INSTITUT FÜR MATHEMATIK, UNIVERSITÄT ZÜRICH, WINTERTHURERSTRASSE 190, CH-8057 ZÜRICH, SWITZERLAND.

E-mail address: anza@math.unizh.ch

“EQUIPE AVA (ANALYSE VARIATIONNELLE ET APPLICATIONS)”, CENTRE UNIVERSITAIRE DE FORMATION ET DE RECHERCHE DE NÎMES, SITE DES CARMES, PLACE GABRIEL PÉRI - CEDEX 01 - 30021 NÎMES, FRANCE.

I3M (INSTITUT DE MATHÉMATIQUES ET MODÉLISATION DE MONTPELLIER) UMR - CNRS 5149, UNIVERSITÉ MONTPELLIER II, PLACE EUGÈNE BATAILLON, 34090 MONTPELLIER, FRANCE.

E-mail address: jean-philippe.mandallena@unimes.fr