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Rosenthal, J ; Zelevinsky, A

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# MULTIPLICITIES OF POINTS ON SCHUBERT VARIETIES IN GRASSMANNIANS

JOACHIM ROSENTHAL AND ANDREI ZELEVINSKY

ABSTRACT. We obtain an explicit determinantal formula for the multiplicity of any point on a classical Schubert variety.

## 1. MAIN RESULT

An important invariant of a singular point on an algebraic variety  $X$  is its *multiplicity*: the normalized leading coefficient of the Hilbert polynomial of the local ring. The main result of the present note is an explicit determinantal formula for the multiplicities of points on Schubert varieties in Grassmannians. This is a simplification of a formula obtained in [5]. More recently, the recurrence relations for multiplicities of points on more general (partial) flag varieties were obtained in [2, 3]. However, to the best of our knowledge the case of Grassmannians remains the only case for which an explicit formula for multiplicities is available.

Fix positive integers  $d$  and  $n$  with  $0 \leq d \leq n$ , and consider the Grassmannian  $Gr_d(V)$  of  $d$ -dimensional subspaces in a  $n$ -dimensional vector space  $V$  (over an algebraically closed field of arbitrary characteristic). Recall that Schubert varieties in  $Gr_d(V)$  are parameterized by the set  $I_{d,n}$  of integer vectors  $\mathbf{i} = (i_1, \dots, i_d)$  such that  $1 \leq i_1 < \dots < i_d \leq n$ . For a given complete flag  $\{0\} = V_0 \subset V_1 \subset \dots \subset V_n = V$ , the Schubert variety  $X_{\mathbf{i}}$  is defined as follows:

$$X_{\mathbf{i}} := \{W \in Gr_d(V) \mid \dim(W \cap V_{i_k}) \geq k \text{ for } k = 1, \dots, d\} .$$

The Schubert cell  $X_{\mathbf{i}}^0$  is an open subset in  $X_{\mathbf{i}}$  given by

$$X_{\mathbf{i}}^0 := \{W \in X_{\mathbf{i}} \mid \dim(W \cap V_{i_k-1}) = k - 1 \text{ for } k = 1, \dots, d\} .$$

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It is well known that the Schubert variety  $X_{\mathbf{i}}$  is the disjoint union of Schubert cells  $X_{\mathbf{j}}^0$  for all  $\mathbf{j} \leq \mathbf{i}$  in the componentwise partial order on  $I_{d,n}$ . The multiplicity of a point  $x$  in  $X_{\mathbf{i}}$  is constant on each Schubert cell  $X_{\mathbf{j}}^0 \subset X_{\mathbf{i}}$ , and we denote this multiplicity by  $M_{\mathbf{j}}(\mathbf{i})$ .

Our main result is the following explicit formula for  $M_{\mathbf{j}}(\mathbf{i})$  (where the binomial coefficients  $\binom{a}{b}$  are subject to the condition that  $\binom{a}{b} = 0$  for  $b < 0$ ):

**Theorem 1.** *The multiplicity  $M_{\mathbf{j}}(\mathbf{i})$  of a point  $x \in X_{\mathbf{j}}^0 \subset X_{\mathbf{i}}$  is given by*

$$(1) \quad M_{\mathbf{j}}(\mathbf{i}) = (-1)^{s_1 + \dots + s_d} \det \begin{bmatrix} \binom{i_1}{-s_1} & \cdots & \cdots & \binom{i_d}{-s_d} \\ \binom{i_1}{1-s_1} & \cdots & \cdots & \binom{i_d}{1-s_d} \\ \vdots & & & \vdots \\ \binom{i_1}{d-1-s_1} & \cdots & \cdots & \binom{i_d}{d-1-s_d} \end{bmatrix},$$

where

$$(2) \quad s_q := \#\{j_p \mid i_q < j_p\}.$$

The proof of Theorem 1 will be given in the next section. Although determinants of matrices formed by binomial coefficients were extensively studied by combinatorialists (see, e.g., [1]), the experts whom we consulted did not recognize the determinant in (1).

We conclude this section by an example illustrating Theorem 1.

**Example 2.** Assume the indices  $\mathbf{i}, \mathbf{j}$  satisfy  $j_d \leq i_1$ . In this situation the numbers  $s_1, \dots, s_d$  attain the smallest possible value:  $s_1 = \dots = s_d = 0$ . Then the  $(p, q)$ -entry of the determinant in (1) has the form  $P_p(i_q)$ , where  $P_p(t)$  is a polynomial with the leading term  $t^{p-1}/(p-1)!$ . It follows that

$$(3) \quad M_{\mathbf{j}}(\mathbf{i}) = \frac{1}{1! \dots (d-1)!} V(\mathbf{i}) = \frac{1}{1! \dots (d-1)!} \prod_{p>q} (i_p - i_q),$$

where  $V(\mathbf{i})$  is the Vandermonde determinant  $\det((i_q^{p-1}))$ .

## 2. PROOF OF THEOREM 1

Fix two vectors  $\mathbf{j} \leq \mathbf{i}$  from  $I_{d,n}$ , and let

$$\deg(\mathbf{j}, \mathbf{i}) := d - \#\{i_q \mid i_q \in \{j_1, \dots, j_d\}\}.$$

For a nonnegative integer vector  $\mathbf{s} = (s_1, \dots, s_d)$ , we set

$$|\mathbf{s}| := s_1 + \dots + s_d.$$

As shown in [5] and [3, page 202], the multiplicity  $M_{\mathbf{j}}(\mathbf{i})$  satisfies the initial condition  $M_{\mathbf{j}}(\mathbf{j}) = 1$  and the partial difference equation

$$(4) \quad M_{\mathbf{j}}(\mathbf{i}) = \frac{1}{\deg(\mathbf{j}, \mathbf{i})} \sum_{\mathbf{k}} M_{\mathbf{j}}(\mathbf{k}) ,$$

where the sum is over all  $\mathbf{k} \in I_{d,n}$  such that  $\mathbf{j} \leq \mathbf{k} < \mathbf{i}$ , and  $|\mathbf{k}| = |\mathbf{i}| - 1$ .

To prove (1), we proceed by induction on  $|\mathbf{i}|$ . The initial step is to verify (1) for  $\mathbf{i} = \mathbf{j}$ . In this case the numbers  $s_1, \dots, s_d$  attain their maximum possible value:  $s_q = d - q$ . It follows that

$$(5) \quad (-1)^{|\mathbf{s}|} \det \begin{bmatrix} 0 & \dots & 0 & 1 \\ \vdots & & 1 & * \\ 0 & \ddots & \ddots & \vdots \\ 1 & * & \dots & * \end{bmatrix} = 1 = M_{\mathbf{j}}(\mathbf{j}) ,$$

as required.

For the inductive step, we introduce some notation. To any nonnegative integer vector  $\mathbf{s} = (s_1, \dots, s_d)$  we associate a polynomial  $P_{\mathbf{s}}(\mathbf{t}) \in \mathbb{Q}[\mathbf{t}] = \mathbb{Q}[t_1, \dots, t_d]$  defined by

$$(6) \quad P_{\mathbf{s}}(\mathbf{t}) = (-1)^{|\mathbf{s}|} \det \begin{bmatrix} \binom{t_1}{-s_1} & \dots & \dots & \binom{t_d}{-s_d} \\ \binom{t_1}{1-s_1} & \dots & \dots & \binom{t_d}{1-s_d} \\ \vdots & & & \vdots \\ \binom{t_1}{d-1-s_1} & \dots & \dots & \binom{t_d}{d-1-s_d} \end{bmatrix} ;$$

here  $\binom{t}{s}$  is the polynomial  $t(t-1)\cdots(t-s+1)/s!$  for  $s \geq 0$ , and  $\binom{t}{s} = 0$  for  $s < 0$ . Thus our goal is to show that  $M_{\mathbf{j}}(\mathbf{i}) = P_{\mathbf{s}}(\mathbf{i})$  with  $\mathbf{s}$  given by (2).

For  $q = 1, \dots, d$ , let  $\Delta_q : \mathbb{Q}[\mathbf{t}] \rightarrow \mathbb{Q}[\mathbf{t}]$  denote the partial difference operator  $\Delta_q P(\mathbf{t}) = P(\mathbf{t}) - P(\mathbf{t} - e_q)$ , where  $e_1, \dots, e_d$  are the unit vectors in  $\mathbb{Q}^d$ . Here is the key lemma.

**Lemma 3.** *For any nonnegative integer vector  $\mathbf{s}$ , the corresponding polynomial  $P_{\mathbf{s}}(\mathbf{t})$  satisfies the partial difference equation*

$$(7) \quad (\Delta_1 + \dots + \Delta_d)P = 0 .$$

*Proof.* First notice that the Vandermonde determinant  $V(\mathbf{t}) = \prod_{p>q} (t_p - t_q)$  satisfies (7) since it is a non-zero skew-symmetric polynomial of minimal possible degree, and the operator  $\Delta_1 + \dots + \Delta_d$  preserves the space of skew-symmetric polynomials. The vector space of solutions of (7) is also invariant

under translations  $\mathbf{t} \mapsto \mathbf{t} + \mathbf{k}$  so it is enough to show that each  $P_{\mathbf{s}}(\mathbf{t})$  is a linear combination of polynomials  $V(\mathbf{t} + \mathbf{k})$ . Here is the desired expression:

$$(8) \quad P_{\mathbf{s}}(\mathbf{t}) = \frac{1}{1! \cdots (d-1)!} \sum_{0 \leq \mathbf{k} \leq \mathbf{s}} (-1)^{|\mathbf{k}|} \binom{s_1}{k_1} \cdots \binom{s_d}{k_d} V(\mathbf{t} + \mathbf{k}) .$$

Let us prove (8). The same argument as in Example 2 above shows that

$$(9) \quad \frac{1}{1! \cdots (d-1)!} V(\mathbf{t} + \mathbf{k}) = \det \begin{bmatrix} \binom{t_1+k_1}{0} & \cdots & \cdots & \binom{t_d+k_d}{0} \\ \binom{t_1+k_1}{1} & \cdots & \cdots & \binom{t_d+k_d}{1} \\ \vdots & & & \vdots \\ \binom{t_1+k_1}{d-1} & \cdots & \cdots & \binom{t_d+k_d}{d-1} \end{bmatrix} .$$

Substituting this expression into (8) and performing the multiple summation, we see that the right hand side becomes the determinant of the  $d \times d$  matrix whose  $(p, q)$ -entry is

$$\sum_{k_q=0}^{s_q} (-1)^{k_q} \binom{s_q}{k_q} \binom{t_q+k_q}{p-1} = (-1)^{s_q} \binom{t_q}{p-1-s_q}$$

(the last equality is a standard binomial identity). This completes the proof of (8) and Lemma 3.  $\square$

One last piece of preparation before performing the inductive step: the Pascal binomial identity  $\binom{t}{s} = \binom{t-1}{s} + \binom{t-1}{s-1}$  implies that

$$(10) \quad \Delta_q P_{\mathbf{s}}(\mathbf{t}) = -P_{\mathbf{s}+e_q}(\mathbf{t} - e_q)$$

for any nonnegative integer vector  $\mathbf{s}$  and any  $q = 1, \dots, d$ .

To conclude the proof of Theorem 1, suppose that  $\mathbf{j} < \mathbf{i}$  and assume by induction that  $M_{\mathbf{j}}(\mathbf{k})$  is given by (1) for any  $\mathbf{k} \in I_{d,n}$  such that  $\mathbf{j} \leq \mathbf{k} < \mathbf{i}$ . Let  $\mathbf{s}$  be the vector given by (2). In view of (4), the desired equality  $M_{\mathbf{j}}(\mathbf{i}) = P_{\mathbf{s}}(\mathbf{i})$  is a consequence of the following:

$$(11) \quad \deg(\mathbf{j}, \mathbf{i}) P_{\mathbf{s}}(\mathbf{i}) - \sum_{\mathbf{k}} M_{\mathbf{j}}(\mathbf{k}) = 0 ,$$

where the sum is over all  $\mathbf{k} \in I_{d,n}$  such that  $\mathbf{j} \leq \mathbf{k} < \mathbf{i}$ , and  $|\mathbf{k}| = |\mathbf{i}| - 1$ .

We shall deduce (11) from the equality

$$\sum_{q=1}^d \Delta_q P_{\mathbf{s}}(\mathbf{i}) = 0$$

provided by Lemma 3. To do this, we compute  $\Delta_q P_{\mathbf{s}}(\mathbf{i})$  in each of the following mutually exclusive cases (we use the conventions  $i_0 = 0$  and  $s_0 = d$ ):

**Case 1:**  $i_q \notin \{j_1, \dots, j_d\}$ ,  $i_q - 1 > i_{q-1}$ . Then  $\mathbf{k} := \mathbf{i} - e_q$  belongs to  $I_{d,n}$ , and we have  $\mathbf{j} \leq \mathbf{k}$ . Replacing  $\mathbf{i}$  by  $\mathbf{k}$  in (2) does not change the vector  $\mathbf{s}$ . By our inductive assumption,  $P_{\mathbf{s}}(\mathbf{k}) = M_{\mathbf{j}}(\mathbf{k})$ , and so  $\Delta_q P_{\mathbf{s}}(\mathbf{i}) = P_{\mathbf{s}}(\mathbf{i}) - M_{\mathbf{j}}(\mathbf{k})$ .

**Case 2:**  $i_q \notin \{j_1, \dots, j_d\}$ ,  $i_q - 1 = i_{q-1}$ . For such  $q$ , we have  $P_{\mathbf{s}}(\mathbf{i} - e_q) = 0$  since the corresponding determinant has the  $(q-1)$ th and  $q$ th columns equal to each other. Thus  $\Delta_q P_{\mathbf{s}}(\mathbf{i}) = P_{\mathbf{s}}(\mathbf{i})$ .

**Case 3:**  $i_q \in \{j_{q+1}, \dots, j_d\}$ ,  $i_q - 1 > i_{q-1}$ . As in Case 1, we have  $\mathbf{k} := \mathbf{i} - e_q \in I_{d,n}$ , and  $\mathbf{j} \leq \mathbf{k}$ . However now replacing  $\mathbf{i}$  by  $\mathbf{k}$  in (2) changes  $\mathbf{s}$  to  $\mathbf{s} + e_q$ . Combining the inductive assumption with (10), we conclude that  $\Delta_q P_{\mathbf{s}}(\mathbf{i}) = -P_{\mathbf{s}+e_q}(\mathbf{k}) = -M_{\mathbf{j}}(\mathbf{k})$ .

**Case 4:**  $i_q \in \{j_{q+1}, \dots, j_d\}$ ,  $i_q - 1 = i_{q-1}$ . In this case, the  $d \times d$  matrix whose determinant is  $P_{\mathbf{s}+e_q}(\mathbf{i} - e_q)$  has the  $(q-1)$ th and  $q$ th columns equal to each other, hence  $\Delta_q P_{\mathbf{s}}(\mathbf{i}) = -P_{\mathbf{s}+e_q}(\mathbf{k}) = 0$ .

**Case 5:**  $i_q = j_q$ . Then we have

$$s_1 \geq s_2 \geq \dots \geq s_{q-1} \geq s_q + 1 = d + 1 - q,$$

and so the  $d \times d$  matrix whose determinant is  $P_{\mathbf{s}+e_q}(\mathbf{i} - e_q)$  has a zero  $(d+1-q) \times q$  submatrix. As in Case 4, this implies  $\Delta_q P_{\mathbf{s}}(\mathbf{i}) = -P_{\mathbf{s}+e_q}(\mathbf{k}) = 0$ .

Adding up the contributions  $\Delta_q P_{\mathbf{s}}(\mathbf{i})$  from all these cases, we obtain (11); this completes the proof of Theorem 1.

**Remark 4.** In [5], the multiplicity  $M_{\mathbf{j}}(\mathbf{i})$  was expressed as a multiple sum given by (8).

**Remark 5.** The multiplicity  $M_{\mathbf{j}}(\mathbf{i})$  is by definition a positive integer. The partial difference equation (4) (combined with the initial condition  $M_{\mathbf{j}}(\mathbf{j}) = 1$ ) makes the positivity of  $M_{\mathbf{j}}(\mathbf{i})$  obvious but the fact that  $M_{\mathbf{j}}(\mathbf{i})$  is an integer becomes rather mysterious. On the other hand, Theorem 1 makes it clear that  $M_{\mathbf{j}}(\mathbf{i})$  is an integer but not that  $M_{\mathbf{j}}(\mathbf{i}) > 0$ . It would be interesting to find an expression for  $M_{\mathbf{j}}(\mathbf{i})$  that makes obvious both properties.

**Remark 6.** The space of all polynomial solutions of the partial difference equation (7) can be described as follows. Let  $\mathbf{y} = (y_1, \dots, y_d)$  be an auxiliary set of variables, and let  $\varphi : \mathbb{Q}[\mathbf{y}] \rightarrow \mathbb{Q}[\mathbf{t}]$  be the isomorphism of vector spaces that sends each monomial  $\prod_{q=1}^d y_q^{n_q}$  to  $\prod_{q=1}^d t_q(t_q + 1) \cdots (t_q + n_q - 1)$ . The map  $\varphi$  intertwines each  $\Delta_q$  with the partial derivative  $\frac{\partial}{\partial y_q}$ . It follows that the space of solutions of (7) is the image under  $\varphi$  of the  $\mathbb{Q}$ -subalgebra in  $\mathbb{Q}[\mathbf{y}]$  generated by all differences  $y_p - y_q$ .

**Remark 7.** Jerzy Weyman informed us about the following determinantal formula (unpublished) for the multiplicity  $M_{\mathbf{j}}(\mathbf{i})$  in the special case when  $\mathbf{j} = (1, 2, \dots, d)$ . Let  $\lambda$  be the partition  $(i_d - d, \dots, i_2 - 2, i_1 - 1)$ , and let  $\lambda = (\alpha_1, \dots, \alpha_r | \beta_1, \dots, \beta_r)$  be the Frobenius notation of  $\lambda$  (see [4]). According to J. Weyman,  $M_{\mathbf{j}}(\mathbf{i})$  is equal to the determinant of the  $r \times r$  matrix whose  $(p, q)$ -entry is  $\binom{\alpha_p + \beta_q}{\alpha_p}$ . It is not immediately clear why this determinantal expression agrees with the one given by (1).

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DEPARTMENT OF MATHEMATICS, UNIVERSITY OF NOTRE DAME, NOTRE DAME, INDIANA 46556

*E-mail address:* `Rosenthal.1@nd.edu`

NORTHEASTERN UNIVERSITY, DEPARTMENT OF MATHEMATICS, BOSTON, MA 02115

*E-mail address:* `andrei@neu.edu`